

Math 323
Linear Algebra and Matrix Theory I
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Key Homework 17

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a) Use the procedure we introduced in class.

```
V=[5 -1; -7 2; 1 -1; 4 -4], R=rref([V eye(4)])
```

V =

```
 5   -1
 -7   2
 1   -1
 4   -4
```

R =

```
1.0000    0    0   -0.2000    0   -0.1000
          0    1.0000    0   -0.2000    0   -0.3500
          0    0    1.0000    0.8000    0    0.1500
          0    0    0    0    1.0000   -0.2500
```

A basis for R^4 is given by the columns of the matrix B below.

```
H=[V eye(4)]; B=H(:, [1 2 3 5])
```

B =

```
 5   -1    1    0
 -7    2    0    0
  1   -1    0    1
  4   -4    0    0
```

b) Since the vectors $\vec{v}_1, \dots, \vec{v}_k$ are linearly independent, none of them can be written as a linear combination of its predecessors. This implies that the first k columns of the matrix obtained by augmenting the V matrix with the identity matrix, will always be pivot columns.

c)

```
hopefully_B=[V randint(4, 2, 5, 2)], check=rank(hopefully_B)
```

hopefully_B =

```
 5   -1    4    3
 -7    2    1    0
  1   -1    0   -3
  4   -4    1    3
```

check =

```
4
```

Because the rank of this matrix equals 4, its columns are linearly independent and form a basis for R^4 .

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a) Use the method explained in class.

$V = [3 \ 4 \ -6 \ 4; \ -4 \ 0 \ 0 \ 8; \ -3 \ -2 \ 3 \ 1; \ 2 \ 6 \ -9 \ 11]$, $R = \text{rref}(V)$

$$V = \begin{bmatrix} 3 & 4 & -6 & 4 \\ -4 & 0 & 0 & 8 \\ -3 & -2 & 3 & 1 \\ 2 & 6 & -9 & 11 \end{bmatrix}$$

$$R = \begin{bmatrix} 1.0000 & 0 & 0 & -2.0000 \\ 0 & 1.0000 & -1.5000 & 2.5000 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

The first two columns are pivot columns, and therefore the first two columns of V form a basis for $C(V)$.

b) Use all sets of two linearly independent columns of V . (observe that the second and the third column are linearly dependent) The desired bases are:

$\{\vec{v}_1, \vec{v}_2\}, \{\vec{v}_1, \vec{v}_3\}, \{\vec{v}_1, \vec{v}_4\}, \{\vec{v}_2, \vec{v}_4\}, \{\vec{v}_3, \vec{v}_4\}$.

c) Take the answer of (b) plus: $\{\vec{v}_1, \vec{v}_2, \vec{v}_3\}, \{\vec{v}_1, \vec{v}_2, \vec{v}_4\}, \{\vec{v}_1, \vec{v}_3, \vec{v}_4\}, \{\vec{v}_2, \vec{v}_3, \vec{v}_4\}, \{\vec{v}_1, \vec{v}_2, \vec{v}_3, \vec{v}_4\}$.

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a)

$V = [3 \ -3 \ 4; \ 4 \ 1 \ 1; \ 1 \ -4 \ 2; \ 3 \ 1 \ 3]$, $W = [-5 \ -1 \ 2; \ 2 \ 8 \ -11; \ -3 \ -4 \ 5; \ -3 \ 4 \ -4]$

$$V = \begin{bmatrix} 3 & -3 & 4 \\ 4 & 1 & 1 \\ 1 & -4 & 2 \\ 3 & 1 & 3 \end{bmatrix}$$

$$W = \begin{bmatrix} -5 & -1 & 2 \\ 2 & 8 & -11 \\ -3 & -4 & 5 \\ -3 & 4 & -4 \end{bmatrix}$$

$X = W \setminus V, \ Y = V \setminus W$

$$X = \begin{bmatrix} -1.0000 & 1.0000 & -1.0000 \\ -2.0000 & 4.0000 & -1.0000 \\ -2.0000 & 3.0000 & -1.0000 \end{bmatrix}$$

$$Y = \begin{bmatrix} 1.0000 & 2.0000 & -3.0000 \\ -0.0000 & 1.0000 & -1.0000 \\ -2.0000 & -1.0000 & 2.0000 \end{bmatrix}$$

Let S_v and S_w denote the span of the v vectors and the w vectors respectively. Since $V = WX$, S_v is a subset of S_w . Similarly because $W = VY$, S_w is a subset of S_v . We conclude that $S_v = S_w$.

b)

$X*Y, Y*X$

```
ans =
    1.0000    0.0000   -0.0000
         0    1.0000   -0.0000
         0         0    1.0000
```

```
ans =
    1.0000    0.0000   -0.0000
         0    1.0000         0
    0.0000   -0.0000    1.0000
```

Since $XY = I$ and $YX = I$, X and Y are each others inverse.

The reason for that is simple: $V = WX$ and $W = VY$ implies that $V = VYX$. This last equation expresses the columns of V as linear combinations of themselves, but since the columns of V are linearly independent, such linear combinations are unique and must therefore be the trivial linear combinations $\vec{v}_1 = \vec{v}_1, \dots, \vec{v}_k = \vec{v}_k$, which means that $XY = I$.

c) Since the set $w = \{\vec{w}_1, \dots, \vec{w}_k\}$ is linearly independent, $\text{span}(w)$ has dimension k . Moreover, since $V = WX$, the linearly independent vectors $\vec{v}_1, \dots, \vec{v}_k$ all belong to $\text{span}(w)$. This implies that $v = \{\vec{v}_1, \dots, \vec{v}_k\}$ is a set of k linearly independent vectors in a vector space, $\text{span}(w)$, of dimension k , which in turn means that v is a basis for $\text{span}(w)$ and consequently $\text{span}(v) = \text{span}(w)$.