

Math 323
Linear Algebra and Matrix Theory I
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Key Homework 20

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$A = \begin{bmatrix} .8 & .3 \\ .2 & .7 \end{bmatrix}$, $A_s = A^2$, $A_i = \begin{bmatrix} .6 & .6 \\ .4 & .4 \end{bmatrix}$

$A =$
0.8000 0.3000
0.2000 0.7000
 $A_s =$
0.7000 0.4500
0.3000 0.5500
 $A_i =$
0.6000 0.6000
0.4000 0.4000

$[V, D] = \text{eig}(A)$, $[V_s, D_s] = \text{eig}(A_s)$, $[V_I, D_I] = \text{eig}(A_i)$

$V =$
0.8321 -0.7071
0.5547 0.7071
 $D =$
1.0000 0
0 0.5000
 $V_s =$
0.8321 -0.7071
0.5547 0.7071
 $D_s =$
1.0000 0
0 0.2500
 $V_I =$
0.8321 -0.7071
0.5547 0.7071
 $D_I =$
1 0
0 0

Observe that all three matrices have the same linearly independent eigenvectors:

$\vec{v}_1 = (0.8321, 0.5547)$, $\vec{v}_2 = (-0.7071, 0.7071)$. The eigenvalues of A^2 are the averages of the corresponding eigenvalues of A and A^∞ . This means that for every vector $\vec{x} \in \mathbb{R}^2$,

$$A^2 \vec{x} = A^2(\alpha_1 \vec{v}_1 + \alpha_2 \vec{v}_2) = \alpha_1 \vec{v}_1 + 0.25 \alpha_2 \vec{v}_2 = \frac{1}{2}(A + A^\infty)(\alpha_1 \vec{v}_1 + \alpha_2 \vec{v}_2) = \frac{1}{2}(A + A^\infty)\vec{x},$$

which implies that $A^2 = \frac{1}{2}(A + A^\infty)$.

a)

```
eig(A), eig(A([2 1], : ))
```

```
ans =  
    1.0000  
    0.5000  
ans =  
   -0.5000  
    1.0000
```

b) A zero eigenvalue indicates that the matrix is singular. Since $\text{rank}(A) = \text{rank}(U) = \text{rank}(\text{rref}(A))$, singularity is not affected by elimination. When A has an eigenvalue zero, the so do U and $\text{rref}(A)$.

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```
A=[1 4; 2 3], [V1, D1]=eig(A), [V2, D2]=eig(A+eye(2))
```

```
A =  
    1    4  
    2    3  
V1 =  
   -0.8944   -0.7071  
    0.4472   -0.7071  
D1 =  
   -1    0  
    0    5  
V2 =  
   -0.8944   -0.7071  
    0.4472   -0.7071  
D2 =  
    0    0  
    0    6
```

$A+I$ has the same eigenvectors as A. Its eigenvalues are increased by 1.

Proof: Let λ be an eigenvalue of A associated with the eigenvector \vec{v} , then $(A+I)\vec{v} = \lambda\vec{v} + \vec{v} = (\lambda+1)\vec{v}$.

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```
A=[-1 3; 2 0], [V, D]=eig(A), [V_s, D_s]=eig(A^2)
```

```
A =  
   -1    3  
    2    0  
V =  
   -0.8321   -0.7071  
    0.5547   -0.7071  
D =  
   -3    0  
    0    2  
V_s =  
    0.8321    0.7071  
   -0.5547    0.7071  
D_s =  
    9    0  
    0    4
```

A^2 has the same eigenvectors as A , when A has eigenvalues λ_1, λ_2 the A^2 has eigenvalues λ_1^2, λ_2^2 . Proof: Let A have the eigenvalue λ corresponding to the eigenvector \vec{v} , then $A^2\vec{v} = A(A\vec{v}) = A(\lambda\vec{v}) = \lambda A\vec{v} = \lambda^2\vec{v}$.

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```
A=[1 0; 1 1]; B=A'; eig(A), eig(B), eigenvalues_product=eig(A).*eig(B),
eigenvalues_AB=eig(A*B), eigenvalues_BA=eig(B*A)
```

```
ans =
     1
     1
ans =
     1
     1
eigenvalues_product =
     1
     1
eigenvalues_AB =
     0.3820
     2.6180
eigenvalues_BA =
     2.6180
     0.3820
```

- Clearly the eigenvalues of a product of matrices do not equal the product of the eigenvalues of those matrices
- The eigenvalues of AB however do equal the eigenvalues of BA . Proof: Let $\lambda \neq 0$ denote an eigenvalue of AB corresponding to the eigenvector \vec{x} , then $AB\vec{x} = \lambda\vec{x}$ implies that $B\vec{x} \neq \vec{0}$. Moreover $AB\vec{x} = \lambda\vec{x} \Rightarrow BA(B\vec{x}) = B(AB\vec{x}) = B(\lambda\vec{x}) = \lambda(B\vec{x})$, which means that λ is also an eigenvalue of BA (with eigenvector $B\vec{x}$). To complete the argument we observe that if $\lambda = 0$ is an eigenvalue of AB , then AB is singular and also BA is singular, since $0 = \det(AB) = \det(BA)$. The latter implies that $\lambda = 0$ is also an eigenvalue of BA

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- ..., the way to find λ is to compute $A\vec{x}$.
- ..., the way to find \vec{x} is to solve $(A - \lambda I)\vec{x} = \vec{0}$.

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- See the key to problem 4 for a proof.
- If λ is an eigenvalue of an invertible matrix A then $\lambda \neq 0$ (otherwise the nullspace of A would contain a non-zero element). Moreover $A\vec{x} = \lambda\vec{x} \Rightarrow \vec{x} = A^{-1}A\vec{x} = A^{-1}(\lambda\vec{x}) = \lambda A^{-1}\vec{x} \Rightarrow A^{-1}\vec{x} = \lambda^{-1}\vec{x}$, so λ^{-1} is an eigenvalue of A^{-1} .
- See the key to problem 2 for a proof.

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$P=[0.2 \ 0.4 \ 0; \ 0.4 \ 0.8 \ 0; \ 0 \ 0 \ 1], [V, D]=\text{eig}(P)$

```

P =
    0.2000    0.4000    0
    0.4000    0.8000    0
         0         0    1.0000
V =
    0.8944    0.4472    0
   -0.4472    0.8944    0
         0         0    1.0000
D =
     0     0     0
     0     1     0
     0     0     1

```

The eigenvalues of P^{100} are $1^{100} = 1$, and $0^{100} = 0$, the eigenvectors are the same as those of P . Observe that P has more than one eigenvector associated with the eigenvalue $\lambda = 1$: $\vec{v}_1 = (0.4472, 0.8944, 0)$ (you could say $\vec{v}_1 = (1, 2, 0)$) and $\vec{v}_2 = (0,0,1)$. This means that any linear combination of \vec{v}_1 and \vec{v}_2 is an eigenvector associated with that eigenvalue. In particular $\vec{v}_1 + \vec{v}_2$ is such eigenvector with no zero components.

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$u=[1/6 \ 1/6 \ 3/6 \ 5/6]', P=u*u'$

```

u =
    0.1667
    0.1667
    0.5000
    0.8333
P =
    0.0278    0.0278    0.0833    0.1389
    0.0278    0.0278    0.0833    0.1389
    0.0833    0.0833    0.2500    0.4167
    0.1389    0.1389    0.4167    0.6944

```

- a) Since u has length 1, $\vec{u}^T \vec{u} = 1$ and $P\vec{u} = \vec{u}\vec{u}^T \vec{u} = \vec{u}1 = \vec{u}$.
b) If $\vec{u}^T \vec{v} = 0$, then $P\vec{v} = \vec{u}\vec{u}^T \vec{v} = \vec{u}0 = \vec{0}$.

c)
nulbasis(P)

```

ans =
   -1   -3   -5
    1    0    0
    0    1    0
    0    0    1

```

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Observe that if A denotes an n by n matrix, the characteristic polynomial $p(\lambda) = \det(A - \lambda I)$ is a polynomial of degree n with leading coefficient $(-1)^n$. (just look at the leading term of

$p(\lambda) = \det(A - \lambda I) = \sum \det(P) (A - \lambda I)_{1,j_1} \cdots (A - \lambda I)_{n,j_n}$. This implies that
 $p(\lambda) = \det(A - \lambda I) = \prod_{j=1}^n (\lambda_j - \lambda)$. Now let $\lambda = 0$ to obtain $\det(A) = \prod_{j=1}^n \lambda_j$.

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- a) $\det(A - \lambda I) = (\lambda - 3)(\lambda - 4) = \lambda^2 - 7\lambda + 12$
- b) .. and $\lambda = (a + d - \sqrt{\dots}) / 2$
- c) ... their sum is $a + d$.

This result will be generalized in the section 6.2.

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- a) Eigenvectors associated with distinct eigenvalues are linearly independent, so the sum of the dimensions of the eigenspaces of any n by n matrix cannot be greater than n. Since the 3 by 3 matrix B has three distinct eigenvalues, the dimension of each of the eigenspaces has to be exactly one. Since the eigenspace associated with the eigenvalue $\lambda = 0$ is exactly the nullspace of B, this means that the rank of B equals $3 - 1 = 2$.
- b) Since $\text{rank}(B) = 2$ and B is 3 by 3, we know that $\det(B) = 0$ and therefore $\det(B^T B) = \det(B^T) \det(B) = 0$.
- c) The eigenvalues of $B^T B$ are not uniquely determined by the eigenvalues of B. As an example of this fact consider the matrices $B_1 = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 2 \\ 0 & 0 & 2 \end{pmatrix}$ and $B_2 = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & 2 \end{pmatrix}$. Both matrices have eigenvalues 0, 1, and 2, but the eigenvalues of $B_1^T B_1$ are 0, 1, and 4, while the eigenvalues of $B_2^T B_2$ are 0, $3 + \sqrt{5}$, and $3 - \sqrt{5}$.
- d) The eigenvalues of $(B + I)^{-1}$ are the reciprocals of the eigenvalues of $B + I$ (which are 1, 2, and 3). The desired eigenvalues are therefore, $1, \frac{1}{2}$ and $\frac{1}{3}$.

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Because all eigenvalues are zero, both the trace and the determinant of the matrix need to be zero. Observe that in the 2 by 2 case, these equations are not only a necessary, but also a sufficient condition for zero to be the only eigenvalue. If $A = \begin{pmatrix} a & b \\ c & -a \end{pmatrix}$, the equation $\det(A) = 0$ quickly leads to the solutions $\{a = a, c = c, b = -\frac{a^2}{c}\}$, or $\{a = 0, c = 0, b = b\}$. It is a matter of elementary arithmetic to show that in each of these two cases $A^2 = O$.
 Examples are $\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}$, and $\begin{pmatrix} 1 & -1 \\ 1 & -1 \end{pmatrix}$ for $\{a, b, c\}$ equal to $\{0, 1, 0\}, \{0, 0, 1\}$, and $\{1, -1, 1\}$ respectively.