Math 323 Linear Algebra and Matrix Theory I Fall 1999

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# Key Homework 21

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S=[1 1; 0 1], L=[2 0; 0 5], A=S\*L\*inv(S) S = 1 1 0 1 L = 2 0 5 0 A = 2 3 5 0

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- a) Not necessarily, because A could have an eigenvalue zero.
- b) Yes, because A has a full set of linearly independent eigenvectors.
- c) Yes, because the columns of S are linearly independent.
- d) Not necessarily, but constructing a counter example takes some effort. We start with an invertible, yet not diagonalizable matrix S.

#### S=[2 1 0; -1 0 1; 1 3 1], Sinv=inv(S), [vS, dS]=eig(S)

```
S =
    2
          1
               0
   -1
         0
               1
               1
    1
          3
Sinv =
   0.7500
          0.2500
                    -0.2500
  -0.5000 -0.5000
                    0.5000
   0.7500 1.2500
                    -0.2500
vS =
                    0.0000 + 0.7071i 0.0000 - 0.7071i
 -0.1961
                   -0.0000 + 0.0000i -0.0000 - 0.0000i
  0.5883
                    0.0000 + 0.7071i 0.0000 - 0.7071i
 -0.7845
dS =
 -1.0000
                                           0
                         0
                                     0
                    2.0000 + 0.0000i
       0
       0
                       0
                                    2.0000 - 0.0000i
```

Now we create a 3 by 3 matrix A such that the eigenvectors of A are the columns of S, with eigenvalues 1, 2 and 3 respectively. (The 1, 2 and 3 are arbitrarily chosen integers). To do this, let B denote the matrix whose columns are the columns of S multiplied by 1, 2, and 3 respectively, then AS = B and  $A = BS^{-1}$ .

This matrix A has the property that the matrix S with the eigenvectors of A as its columns, is invertible, yet not diagonalizable.

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... A is a diagonal matrix.

... It followes directly from the Gauss Jordan elimnation process, that if S is (upper or lower) triangular and invertible, then  $S^{-1}$  is also (upper or lower) triangular. In this case so are SA and SAS<sup>-1</sup>.

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Similar to the procedure followed in problem 5, let  $S = \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$  and  $B = \begin{bmatrix} a & b \\ a & -b \end{bmatrix}$ , then

$$A = BS^{-1} = \frac{\frac{a}{2} + \frac{b}{2}}{\frac{a}{2} - \frac{b}{2}} = \frac{a}{2} + \frac{b}{2}}{\frac{a}{2} - \frac{b}{2}} = \frac{c}{d} + \frac{d}{c}$$

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Look at the characteristic polynomial of the Fibonacci matrix  $A = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$ ,  $p(\lambda) = \lambda^2 - \lambda - 1$ . This implies that  $\lambda_i^2 = \lambda_i + 1 \Rightarrow \lambda_i^{k+2} = \lambda_i^{k+1} + \lambda_i^k$ ,  $i = 1, 2, k = 1, 2, \cdots$ .

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...  $A^{20}(\vec{x}_1 + \vec{x}_2) = \lambda_1^{20}\vec{x}_1 + \lambda_2^{20}\vec{x}_2$  and its second component equals  $\lambda_1^{20} + \lambda_2^{20}$ , which is easily computed to be:

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a) True! Because the matrix A does not have zero as an eigenvalue.

b) False! Because, the matrix could either be, or not be, diagonalizable. In the example below the matrix  $A_1$  is diagonalizable, but the matrix  $A_2$  is not. However both matrices have 2, 2, and 5 as their eigenvectors.

2	0	0		2	1	0
$A_{1} = 0$	2	0	and	$A_{2} = 0$	2	0
0	0	5		0	0	5

We check this claim using MATLAB.

```
A1=[2 0 0; 0 2 0; 0 0 5], [V1, D1]=eig(A1)
```

A1	=		
	2	0	0
	0	2	0
	0	0	5
V1	=		
	1	0	0
	0	1	0
	0	0	1
D1	=		
	2	0	0
	0	2	0
	0	0	5

While

A2=[2 1 0; 0 2 0; 0 0 5], [V2, D2]=eig(A2) A2 = V2 = 1.0000 -1.0000 0.0000 1.0000 D2 = 

c) False! See the answer to (b).

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The matrix  $A = \begin{bmatrix} 3 & 1 \\ 0 & 3 \end{bmatrix}$ , is not diagonalizable because the rank of (A - 3I) equals one (and not zero). **A=[3 1; 0 3], r=rank(A-3\*eye(2))** A =  $\begin{bmatrix} 3 & 1 \\ 0 & 3 \end{bmatrix}$ r =

Changing one of the 3's will create distinct eigenvalues, and linearly independent eigenvectors. Changing the 0 will have the same effect.

Observe that changing the 1 will have NO effect on  $det(A - \lambda I)$ , so the one and only eigenvalue will remain 3. Moreover, if the change is just 0.1, the rank of (A - 3I) will still be one.

However if we were to change the one to a zero, then the rank of (A - 3I) would be zero and the matrix would be diagonalizable. (in fact: it would already be diagonal)

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... since the left side has trace zero. (the diagonal elements of AB are equal to the diagonal elements of BA)

We find a scalar *a* such that if  $E = \begin{bmatrix} 1 & 0 \\ a & 1 \end{bmatrix}$ , then  $EE^T - E^T E = \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix}$ . This equation implies that  $\begin{bmatrix} -a^2 & 0 \\ 0 & a^2 \end{bmatrix} = \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix}$ . We can take *a* equal to 1 or -1.

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```
A=[5 4; 4 5], [VA, DA]=eig(A)

A =

5 4

4 5

VA =

0.7071 0.7071

-0.7071 0.7071

DA =

1 0

0 9
```

We now compute a matrix square root of A and check the result.

Of course the matrix B has no real matrix square root, because the square root of -1 is not real. However a complex square root can easily be computed.

```
B=[4 5; 5 4], [VB, DB]=eig(B), RB=VB*sqrt(DB)*inv(VB), checkB=RB^2
```

```
B =
    4
          5
    5
          4
VB =
   0.7071 0.7071
  -0.7071
             0.7071
DB =
         0
   -1
    0
          9
RB =
  1.5000 + 0.5000i 1.5000 - 0.5000i
  1.5000 - 0.5000i 1.5000 + 0.5000i
checkB =
    4
          5
    5
          4
```

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Unfortunately these matrices are not in the list of our **eigshow** command. (Sorry !!!) All we can do is: compute the eigenvalues and eigenvectors and use the so generated information to answer the questions.

```
A=[2 0; 1.5 0.5], [V, D]=eig(A)
```

1a) The eigenvalues are distinct, so the eigenvectors are linearly independent, and the eigenvalues are real and non-zero, so  $\vec{x}$  and  $A\vec{x}$  will line up four times 1b) The eigenvalues are 0.5 and 2.

1d) The eigenvectors are linearly independent, so A is diagonalizable.

```
A=[-2 1; 1 -2], [V, D]=eig(A)

A =

-2 1

1 -2

V =

0.7071 0.7071

-0.7071 0.7071

D =

-3.0000 0

0 -1.0000
```

2a) The eigenvalues are again distinct, so the eigenvectors are linearly independent, and the eigenvalues are real and non-zero, so  $\vec{x}$  and  $A\vec{x}$  will line up four times.

2b) The eigenvalues are -3 and -1.

2d) The eigenvectors are linearly independent, so A is diagonalizable.

```
A=[-1 2; -2 4], [V, D]=eig(A)
```

```
A = \begin{bmatrix} -1 & 2 \\ -2 & 4 \end{bmatrix}
V = \begin{bmatrix} -0.8944 & -0.4472 \\ -0.4472 & -0.8944 \end{bmatrix}
D = \begin{bmatrix} 0 & 0 \\ 0 & 3 \end{bmatrix}
```

3a) The eigenvalues are again distinct, so the eigenvectors are linearly independent, moreover since the eigenvalues are real, but one of them is zero,  $\vec{x}$  and  $A\vec{x}$  will line up two times.

3b) The eigenvalues are 0 and 3.

3d) The eigenvectors are linearly independent, so A is diagonalizable.

#### A=[1 -1; 1 1], [V, D]=eig(A)

```
A =

1 -1

1 1

V =

-0.7071 -0.7071

0 + 0.7071i 0 - 0.7071i

D =

1.0000 + 1.0000i 0

1.0000 - 1.0000i
```

4a) The eigenvalues are distinct, so the eigenvectors are linearly independent, however the eigenvalues are complex, so  $\vec{x}$  and  $A\vec{x}$  will never line up.

- 4b) The eigenvalues are 1 + i and 1 i.
- 4d) The eigenvectors are linearly independent, so A is diagonalizable.

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a)

A=gallery(5)

A =					
	-9	11	-21	63	-252
	70	-69	141	-421	1684
	-575	575	-1149	3451	-13801
	3891	-3891	7782	-23345	93365
	1024	-1024	2048	-6144	24572

#### e=eig(A)

e =					
-	0.0328	3 + 0.0	)243i		
-	0.0328	3 - 0.0	)243i		
	0.013	) + 0.0	)379i		
	0.0130	0.0	)379i		
	0.039	5			
A5=	A^5, e	e5=eig	(A5)		
A5	=				
	0	0	0	0	0
	0	0	0	0	0
	0	0	0	0	0
	0	0	0	0	0
	0	0	0	0	0
e5	=				
	0				
	0				
	0				
	0				
	0				

Obviously this contradicts our expectation that that the eigenvalues of  $A^5$  are the fifth power of the eigenvalues of A. (the discrepancy occurs because of difficulties with the numeric calculation of the eigenvalues of A)

These results are equally unsatisfactory.

c) Since the matrix A has integer entries, the characteristic polynomial  $p(\lambda) = \det(A - \lambda I)$  must have integer coefficients.

```
p=round(p), roots(p)
```

```
p =

1 0 0 0 0 0

ans =

0

0

0

0

0

0

0

0
```

That's more like it !!!

The roots of a polynomial can be extremely sensitive to changes in the coefficients. A very small change (roundoff error) in the coefficients may result in a significant change in the roots. That is what causes the erroneous answers in (a) and (b).

d) Proof: Let *B* be nilpotent of order *k* and suppose that *B* has an non-zero eigenvalue  $\lambda$ . Then  $\exists \vec{x} \neq \vec{0}$  such that  $B\vec{x} = \lambda \vec{x} \Rightarrow B^k \vec{x} = \lambda^k \vec{x} \neq \vec{0}$ . This clearly contradicts the fact

that B is nilpotent of order k. Therefore our assumption that B has a non-zero eigenvalue must be false, and zero is the only eigenvalue of B.

```
e)
```

```
R=rref(A)
```

```
R =
```

1.0000	0	0	0	0
0	1.0000	0	0	-0.0820
0	0	1.0000	0	0.5547
0	0	0	1.0000	-3.8008
0	0	0	0	0

Clearly rank(A) = 4, and the nullity ( that is the dimension of the nullspace) of A is 5 - 4 = 1. This implies that the geometric multiplicity of the eigenvalue  $\lambda = 0$  equals 1, which is nowhere near its algebraic multiplicity 5, so A is not diagonalizable.