

# Key Homework 16

Math 277, Fall 2005

## Ordinary Differential Equations

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### - Initializations

```
> restart;
```

### - 13: Page 177

Code the differential equation and compute the auxiliary equation.

```
> deq:=diff(y(t),t$2)+2*diff(y(t),t)+5*y(t)=0;
```

$$deq := \left( \frac{d^2}{dt^2} y(t) \right) + 2 \left( \frac{d}{dt} y(t) \right) + 5 y(t) = 0$$

```
> aux_eq:=simplify(eval(subs(y(t)=exp(r*t),deq))/exp(r*t));
```

$$aux\_eq := r^2 + 2r + 5 = 0$$

Solve the auxiliary equation and find the eigenvalues.

```
> evals:=solve(aux_eq,r);
```

$$evals := -1 + 2I, -1 - 2I$$

Code the corresponding solutions and create the general solution.

```
> Y[1]:=exp(Re(evals[1])*t)*cos(Im(evals[1])*t);
```

```
Y[2]:=exp(Re(evals[1])*t)*sin(Im(evals[1])*t);
```

$$Y_1 := e^{(-t)} \cos(2t)$$

$$Y_2 := e^{(-t)} \sin(2t)$$

The general solution is given by an arbitrary linear combination of  $Y_1$  and  $Y_2$ .

```
> ans[13]:=yg=add(c[k]*Y[k],k=1..2);
```

$$ans_{13} := yg = c_1 e^{(-t)} \cos(2t) + c_2 e^{(-t)} \sin(2t)$$

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To solve the given initial value problem, we first compute the general solution of the differential equation and then implement the initial conditions.

#### - The general solution of the differential equation

Code the differential equation and compute the auxiliary equation.

```
> deq:=diff(y(t),t$2)+2*diff(y(t),t)+17*y(t)=0;
```

$$deq := \left( \frac{d^2}{dt^2} y(t) \right) + 2 \left( \frac{d}{dt} y(t) \right) + 17 y(t) = 0$$

```
> aux_eq:=simplify(eval(subs(y(t)=exp(r*t),deq))/exp(r*t));
```

$$aux\_eq := r^2 + 2r + 17 = 0$$

Solve the auxiliary equation and find the eigenvalues.

```
> evals:=solve(aux_eq,r);
```

$$evals := -1 + 4I, -1 - 4I$$

Code the corresponding solutions and create the general solution.

```
> Y[1]:=exp(Re(evals[1])*t)*cos(Im(evals[1])*t);
```

```
Y[2]:=exp(Re(evals[1])*t)*sin(Im(evals[1])*t);
```

$$Y_1 := e^{(-t)} \cos(4t)$$

```

[
[

$$Y_2 := e^{(-t)} \sin(4t)$$

[ The general solution is given by an arbitrary linear combination of  $Y_1$  and  $Y_2$ .
[ > yg:=add(c[k]*Y[k], k=1..2);
[

$$yg := c_1 e^{(-t)} \cos(4t) + c_2 e^{(-t)} \sin(4t)$$

[ >

```

### Implementation of the initial conditions $y(0) = 1, y'(0) = -1$

```

[ > eq1:=eval(subs(t=0, yg))=1;
[ eq2:=eval(subs(t=0, diff(yg, t)))=-1;
[ val_c:=solve({eq1, eq2}, {c[1], c[2]});
[

$$eq1 := c_1 = 1$$


$$eq2 := -c_1 + 4c_2 = -1$$


$$val\_c := \{c_1 = 1, c_2 = 0\}$$

[ The solution of the initial value problem is given by
[ > ans[22]:=y=subs(val_c, yg);
[

$$ans_{22} := y = e^{(-t)} \cos(4t)$$

[ >

```

## 31 (b): Page 177

The initial value problem

$$y'' + 100y' + y = 0, y(0) = 1, y'(0) = 0$$

represents a damped mass-spring system with a very large damping coefficient  $b = 100$ . Since  $0 < b^2 - 4mk$ , the solution will not oscillate, but it will exponentially approach zero. We verify these observations by solving the initial value problem in a manner similar to that used in Problem 22.

### The general solution of the differential equation

```

[ Code the differential equation and compute the auxiliary equation.
[ > deq:=diff(y(t), t$2)+100*diff(y(t), t)+y(t)=0;
[

$$deq := \left(\frac{d^2}{dt^2} y(t)\right) + 100 \left(\frac{d}{dt} y(t)\right) + y(t) = 0$$

[ > aux_eq:=simplify(eval(subs(y(t)=exp(r*t), deq))/exp(r*t));
[

$$aux\_eq := r^2 + 100r + 1 = 0$$

[ Solve the auxiliary equation and find the eigenvalues.
[ > evals:=solve(aux_eq, r);
[

$$evals := -50 + 7\sqrt{51}, -50 - 7\sqrt{51}$$

[ Since the eigenvalues are real and distinct, the corresponding solutions are exponential functions.
[ > for k to 2 do
[ Y[k]:=exp(evals[k]*t);
[ od;
[

$$Y_1 := e^{((-50+7\sqrt{51})t)}$$


$$Y_2 := e^{((-50-7\sqrt{51})t)}$$

[ The general solution is given by a arbitrary linear combination of  $Y_1$  and  $Y_2$ .
[ > yg:=add(c[k]*Y[k], k=1..2);
[

$$yg := c_1 e^{((-50+7\sqrt{51})t)} + c_2 e^{((-50-7\sqrt{51})t)}$$

[ >

```

### Implementation of the initial conditions $y(0) = 1, y'(0) = 0$

```

[ > eq1:=eval(subs(t=0, yg))=1;
[ eq2:=eval(subs(t=0, diff(yg, t)))=0;
[ val_c:=solve({eq1, eq2}, {c[1], c[2]});

```

$$eq1 := c_1 + c_2 = 1$$

$$eq2 := c_1 (-50 + 7\sqrt{51}) + c_2 (-50 - 7\sqrt{51}) = 0$$

$$val\_c := \{c_2 = -\frac{25\sqrt{51}}{357} + \frac{1}{2}, c_1 = \frac{25\sqrt{51}}{357} + \frac{1}{2}\}$$

The solution of the initial value problem is given by

```
> ans[`31b`] := y = subs(val_c, yg);
evalf(ans[`31b`]);
```

$$ans_{31b} := y = \left(\frac{25\sqrt{51}}{357} + \frac{1}{2}\right) e^{((-50+7\sqrt{51})t)} + \left(-\frac{25\sqrt{51}}{357} + \frac{1}{2}\right) e^{((-50-7\sqrt{51})t)}$$

$$y = 1.000100030 e^{(-0.01000100 t)} - 0.0001000300 e^{(-99.98999900 t)}$$

Since, in both terms, the exponents are negative

$$\lim_{t \rightarrow \infty} y(t) = 0.$$

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### 32a

We solve the initial value problem  $10y'' + 250y = 0$ ,  $y(0) = .3$ ,  $y'(0) = -.1$

#### The general solution of the differential equation

Code the differential equation and compute the auxiliary equation.

```
> deq := 10*diff(y(t), t$2) + 250*y(t) = 0;
```

$$deq := 10 \left( \frac{d^2}{dt^2} y(t) \right) + 250 y(t) = 0$$

```
> aux_eq := simplify(eval(subs(y(t) = exp(r*t), deq) / exp(r*t)));
```

$$aux\_eq := 10r^2 + 250 = 0$$

Solve the auxiliary equation and find the eigenvalues.

```
> evals := solve(aux_eq, r);
```

$$evals := 5I, -5I$$

Since the eigenvalues purely imaginary, the corresponding solutions are trigonometric functions.

```
> Y[1] := cos(Im(eval(evals[1])*t));
Y[2] := sin(Im(eval(evals[1])*t);
```

$$Y_1 := \cos(5t)$$

$$Y_2 := \sin(5t)$$

The general solution is given by an arbitrary linear combination of  $Y_1$  and  $Y_2$ .

```
> yg := add(c[k]*Y[k], k=1..2);
```

$$yg := c_1 \cos(5t) + c_2 \sin(5t)$$

#### Implementation of the initial conditions $y(0) = .3$ , $y'(0) = -.1$

```
> eq1 := eval(subs(t=0, yg)) = 0.3;
eq2 := eval(subs(t=0, diff(yg, t))) = -0.1;
val_c := solve({eq1, eq2}, {c[1], c[2]});
```

$$eq1 := c_1 = 0.3$$

$$eq2 := 5c_2 = -0.1$$

$$val\_c := \{c_1 = 0.3000000000, c_2 = -0.02000000000\}$$

The equation of motion for this undamped vibrating spring is given by

```
> ans[`32a`] := y = subs(val_c, yg);
```

$$ans_{32a} := y = 0.3000000000 \cos(5t) - 0.02000000000 \sin(5t)$$

**32b**

The frequency of the oscillation equals

$$\frac{\beta}{2\pi} = \frac{5}{2\pi}$$

**33: Page 177****33a**

We solve the initial value problem  $10y'' + 60y' + 250y = 0$ ,  $y(0) = .3$ ,  $y'(0) = -.1$

**The general solution of the differential equation**

Code the differential equation and compute the auxiliary equation.

```
> deq:=10*diff(y(t),t$2)+60*diff(y(t),t)+250*y(t)=0;
```

$$deq := 10 \left( \frac{d^2}{dt^2} y(t) \right) + 60 \left( \frac{d}{dt} y(t) \right) + 250 y(t) = 0$$

```
> aux_eq:=simplify(eval(subs(y(t)=exp(r*t),deq)/exp(r*t)));
```

$$aux\_eq := 10r^2 + 60r + 250 = 0$$

Solve the auxiliary equation and find the eigenvalues.

```
> evals:=solve(aux_eq,r);
```

$$evals := -3 + 4I, -3 - 4I$$

Observe that the complex eigenvalues now have a nonzero real part. Hence, the solutions are exponentially damped oscillations.

```
> Y[1]:=exp(Re(eval(evals[1])*t))*cos(Im(eval(evals[1])*t));
```

```
Y[2]:=exp(Re(eval(evals[1])*t))*sin(Im(eval(evals[1])*t));
```

$$Y_1 := e^{(-3t)} \cos(4t)$$

$$Y_2 := e^{(-3t)} \sin(4t)$$

The general solution is given by an arbitrary linear combination of  $Y_1$  and  $Y_2$ .

```
> yg:=add(c[k]*Y[k],k=1..2);
```

$$yg := c_1 e^{(-3t)} \cos(4t) + c_2 e^{(-3t)} \sin(4t)$$

**Implementation of the initial conditions  $y(0) = .3$ ,  $y'(0) = -.1$** 

```
> eq1:=eval(subs(t=0,yg))=0.3;
```

```
eq2:=eval(subs(t=0,diff(yg,t)))=-0.1;
```

```
val_c:=solve({eq1,eq2},{c[1],c[2]});
```

$$eq1 := c_1 = 0.3$$

$$eq2 := -3c_1 + 4c_2 = -0.1$$

$$val\_c := \{c_1 = 0.3000000000, c_2 = 0.2000000000\}$$

The equation of motion for this undamped vibrating spring is given by

```
> ans[`32a`] := y = subs(val_c, yg);
```

$$ans_{32a} := y = 0.3000000000 e^{(-3t)} \cos(4t) + 0.2000000000 e^{(-3t)} \sin(4t)$$

**33b**

The frequency of the oscillation equals

$$\frac{\beta}{2\pi} = \frac{4}{2\pi} = \frac{2}{\pi}$$

**33c**

Clearly, the damping has caused the frequency of the oscillation to diminish. In addition the oscillation is now exponentially

damped, so

$$\lim_{t \rightarrow \infty} y(t) = 0$$

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Observe that, since  $\frac{dq}{dt} = I$ , differentiation of both sides of the differential equation

$$L \frac{d^2 q}{dt^2} + R \frac{dq}{dt} + \frac{1}{C} q = E$$

will lead to

$$L \frac{d^2 I}{dt^2} + R \frac{dI}{dt} + \frac{1}{C} I = \frac{dE}{dt}$$

and if the electromotive force  $E$  is a constant, then  $\frac{dE}{dt} = 0$ , so the last equation becomes homogeneous.

### The solution of the homogeneous equation.

Because Maple uses the letter  $I$  for the imaginary unit, we will denote the current at time  $t$  by  $i(t)$ .

```
> pars := {L=10, R=20, C=1/6260};  
deq_general := L*diff(i(t), t$2) + R*diff(i(t), t) + i(t)/C = 0;  
deq := subs(pars, deq_general);
```

$$\text{pars} := \{L = 10, R = 20, C = \frac{1}{6260}\}$$

$$\text{deq\_general} := L \left( \frac{d^2}{dt^2} i(t) \right) + R \left( \frac{d}{dt} i(t) \right) + \frac{i(t)}{C} = 0$$

$$\text{deq} := 10 \left( \frac{d^2}{dt^2} i(t) \right) + 20 \left( \frac{d}{dt} i(t) \right) + 6260 i(t) = 0$$

Find the auxiliary equation and compute the eigenvalues.

```
> aux_eq := simplify(eval(subs(i(t)=exp(r*t), deq))/exp(r*t));  
aux_eq := 10 r^2 + 20 r + 6260 = 0
```

```
> evals := solve(aux_eq, r);
```

$$\text{evals} := -1 + 25 I, -1 - 25 I$$

Code the corresponding solutions and generate the general solution of the homogeneous equation.

```
> Y[1] := exp(Re(evals[1])*t) * cos(Im(evals[1])*t);  
Y[2] := exp(Re(evals[1])*t) * sin(Im(evals[1])*t);
```

$$Y_1 := e^{(-t)} \cos(25 t)$$

$$Y_2 := e^{(-t)} \sin(25 t)$$

```
> ig := add(c[k]*Y[k], k=1..2);
```

$$\text{ig} := c_1 e^{(-t)} \cos(25 t) + c_2 e^{(-t)} \sin(25 t)$$

### Implementation of the initial conditions

Since it is given that the current at time zero is equal to zero, the first initial condition is

$$i(0) = 0$$

To find a value for  $i'(0)$  we have to do a little more work. Note it is given that  $I(0) = 0$ ,  $q(0) = 0$  and  $E(t) = 100$ . We can substitute these values in equation (20)

$$(20) \quad L \frac{dI}{dt} + RI + \frac{1}{C} q = E$$

and find

$$10 \left. \frac{dI}{dt} \right|_{t=0} = 100$$

so

$$i'(0) = 10$$

```
> eq1:=eval(subs(t=0, ig))=0;  
eq2:=eval(subs(t=0, diff(ig, t)))=10;  
val_c:=solve({eq1, eq2}, {c[1], c[2]});
```

$$eq1 := c_1 = 0$$

$$eq2 := -c_1 + 25 c_2 = 10$$

$$val\_c := \{c_1 = 0, c_2 = \frac{2}{5}\}$$

```
> ans[34]:=i(t)=subs(val_c, ig);
```

$$ans_{34} := i(t) = \frac{2}{5} e^{(-t)} \sin(25 t)$$

```
>
```