

## Lesson 11

### Variation of Parameters

#### Initializations

```
> restart;
```

#### 11.1 Variation of Parameters

When the right hand side  $f(t)$  of the differential equation

$$a y'' + b y' + c y = f(t)$$

does not have a simple differential family, then the method of undetermined coefficients will not apply. Instead we may proceed as follows. Suppose  $y_1(t)$  and  $y_2(t)$  denote two linearly independent solutions of the corresponding homogeneous equation. Then we try a particular solution of the form

$$y_p(t) = v_1(t)y_1(t) + v_2(t)y_2(t)$$

Compute  $y_p'(t)$  as

$$y_p'(t) = v_1'(t)y_1(t) + v_2'(t)y_2(t) + v_1(t)y_1'(t) + v_2(t)y_2'(t)$$

Now let

$$v_1'(t)y_1(t) + v_2'(t)y_2(t) = 0$$

This allows us to simplify  $y_p'(t)$  to

$$y_p'(t) = v_1(t)y_1'(t) + v_2(t)y_2'(t)$$

and

$$y_p''(t) = v_1'(t)y_1'(t) + v_2'(t)y_2'(t) + v_1(t)y_1''(t) + v_2(t)y_2''(t)$$

Substitution of  $y_p(t)$ ,  $y_p'(t)$ , and  $y_p''(t)$  into the inhomogeneous differential equation, leads to a second equation for  $v_1'(t)$  and  $v_2'(t)$ . The two equations for  $v_1'(t)$  and  $v_2'(t)$  can be solved simultaneously and after integration of the result we obtain a desired particular solution of the given inhomogeneous equation.

This method is illustrated in the example below. Mathematical details will be provided in class.

#### Examples

##### Example 11.1.1

Solve the initial value problem

$$y'' - 2y' + y = t^{-1}e^t \quad y(1) = 1, y'(1) = -2$$

**Solution**

First we determine the roots of the auxiliary equation of the corresponding homogeneous equation.

```
> aux:=r^2-2*r+1=0;  
ev:=solve(aux, r);
```

$$aux := r^2 - 2r + 1 = 0$$

$$ev := 1, 1$$

(2.1.1.1)

We conclude that  $y_1(t) = e^t$  and  $y_2(t) = te^t$  are two linearly independent solutions of the homogeneous equation. The general solution of the homogeneous equation is given by

$$y_{gh}(t) = c_1 y_1(t) + c_2 y_2(t) = c_1 e^t + c_2 t e^t$$

> **y1:=exp(t);**

**y2:=t\*exp(t);**

**ygh:=c[1]\*y1+c[2]\*y2;**

$$y1 := e^t$$

$$y2 := t e^t$$

$$ygh := c_1 e^t + c_2 t e^t$$

(2.1.1.2)

To find a particular solution of the inhomogeneous equation we try an expression of the form

$$y_p(t) = v_1(t)y_1(t) + v_2(t)y_2(t)$$

Code this expression and its derivative.

> **ytry:=v[1](t)\*y1+v[2](t)\*y2;**

**ytryp:=diff(ytry, t);**

$$ytry := v_1(t) e^t + v_2(t) t e^t$$

$$ytryp := \left( \frac{d}{dt} v_1(t) \right) e^t + v_1(t) e^t + \left( \frac{d}{dt} v_2(t) \right) t e^t + v_2(t) e^t + v_2(t) t e^t \quad (2.1.1.3)$$

The key to success is to let

$$\left( \frac{d}{dt} v_1(t) \right) e^t + \left( \frac{d}{dt} v_2(t) \right) e^t t = 0$$

and use this condition to simplify  $y_p'(t)$ .

> **eq1:=op(1, ytryp)+op(3, ytryp)=0;**

$$eq1 := \left( \frac{d}{dt} v_1(t) \right) e^t + \left( \frac{d}{dt} v_2(t) \right) t e^t = 0$$

(2.1.1.4)

> **ytryp:=ytryp-lhs(eq1);**

$$ytryp := v_1(t) e^t + v_2(t) e^t + v_2(t) t e^t$$

(2.1.1.5)

Differentiate this result to compute  $y_p''(t)$ .

> **ytrypp:=diff(ytryp, t);**

$$ytrypp := \left( \frac{d}{dt} v_1(t) \right) e^t + v_1(t) e^t + \left( \frac{d}{dt} v_2(t) \right) e^t + 2 v_2(t) e^t$$

(2.1.1.6)

$$+ \left( \frac{d}{dt} v_2(t) \right) t e^t + v_2(t) t e^t$$

A second equation for  $v_1'(t)$  and  $v_2'(t)$  is obtained by substituting  $y_p(t)$ ,  $y_p'(t)$ , and  $y_p''(t)$  into the differential equation.

> **deq:=diff(y(t), t\$2)-2\*diff(y(t), t)+y(t)=exp(t)/t;**

**eq2:=simplify(eval(deq, {y(t)=ytry, diff(y(t), t)=ytryp,**

```
diff(y(t), t$2)=ytrypp));
```

$$deq := \frac{d^2}{dt^2} y(t) - 2 \left( \frac{d}{dt} y(t) \right) + y(t) = \frac{e^t}{t}$$

$$eq2 := e^t \left( \frac{d}{dt} v_1(t) + \frac{d}{dt} v_2(t) + \left( \frac{d}{dt} v_2(t) \right) t \right) = \frac{e^t}{t} \quad (2.1.1.7)$$

Now solve the equations **eq1** and **eq2** for  $v_1'(t)$  and  $v_2'(t)$ .

```
> soldv:=solve({eq1, eq2}, {diff(v[1](t), t), diff(v[2](t), t)});
```

$$soldv := \left\{ \frac{d}{dt} v_1(t) = -1, \frac{d}{dt} v_2(t) = \frac{1}{t} \right\} \quad (2.1.1.8)$$

Integrate these equations to find  $v_1(t)$  and  $v_2(t)$ . Since we need only one particular solution we can take the integration constants equal to zero.

```
> v1:=map(int, soldv[1], t);
```

```
v2:=map(int, soldv[2], t);
```

$$v1 := v_1(t) = -t$$

$$v2 := v_2(t) = \ln(t) \quad (2.1.1.9)$$

Hence, a particular solution is given by

```
> yp:=eval(ytry, {v1, v2});
```

$$yp := -t e^t + \ln(t) t e^t \quad (2.1.1.10)$$

and a general solution of the inhomogeneous equation is of the form

```
> yg:=ygh+yp;
```

$$yg := c_1 e^t + c_2 t e^t - t e^t + \ln(t) t e^t \quad (2.1.1.11)$$

Finally, we implement the initial conditions and determine the constants  $c_1$  and  $c_2$ .

```
> eqc1:=eval(yg, t=1)=1;
```

```
eqc2:=eval(diff(yg, t), t=1)=-2;
```

```
val_c:=solve({eqc1, eqc2}, {c[1], c[2]});
```

$$eqc1 := c_1 e + c_2 e - e = 1$$

$$eqc2 := c_1 e + 2 c_2 e - e = -2$$

$$val\_c := \left\{ c_1 = \frac{4+e}{e}, c_2 = -\frac{3}{e} \right\} \quad (2.1.1.12)$$

The solution to the given initial value problem is

```
> ans:=y(t)=eval(yg, val_c);
```

$$ans := y(t) = \frac{(4+e) e^t}{e} - \frac{3 t e^t}{e} - t e^t + \ln(t) t e^t \quad (2.1.1.13)$$