

## Lesson 12

### Systems of Differential Equations

#### Initializations

```
> restart;
```

## 12.1 Systems of Differential Equations with Constant Coefficients

### Examples

#### Example 12.1.1

Solve the initial value problem

$$\frac{dx}{dt} = -7x + 10y + t$$

$$\frac{dy}{dt} = -3x + 4y + 1$$

$$x(0) = 5, y(0) = -4$$

#### Solution 1

There are a variety of ways in which a system like this can be solved. We start with the most intuitive. Solve the first equation for  $y(t)$  and substitute the result into the second equation.

This produces a second order differential equation for  $x(t)$ .

```
> deq1:=diff(x(t), t)+7*x(t)-10*y(t)-t=0;  
deq2:=diff(y(t), t)+3*x(t)-4*y(t)-1=0;
```

$$deq1 := \frac{d}{dt} x(t) + 7x(t) - 10y(t) - t = 0$$

$$deq2 := \frac{d}{dt} y(t) + 3x(t) - 4y(t) - 1 = 0 \quad (2.1.1.1)$$

```
> y_x:=isolate(deq1, y(t));  
deq3:=eval(deq2, y_x);
```

$$y_x := y(t) = \frac{1}{10} \frac{d}{dt} x(t) + \frac{7}{10} x(t) - \frac{1}{10} t$$

$$deq3 := \frac{1}{10} \frac{d^2}{dt^2} x(t) + \frac{3}{10} \frac{d}{dt} x(t) - \frac{11}{10} + \frac{1}{5} x(t) + \frac{2}{5} t = 0 \quad (2.1.1.2)$$

A little bit of handy work can simplify the appearance of this expression.

```
> deq4:=10*deq3;
```

(2.1.1.3)

$$\text{deq4} := \frac{d^2}{dt^2} x(t) + 3 \left( \frac{d}{dt} x(t) \right) - 11 + 2 x(t) + 4 t = 0 \quad (2.1.1.3)$$

> `deq5:=map(u->u+11-4*t, deq4);`

$$\text{deq5} := \frac{d^2}{dt^2} x(t) + 3 \left( \frac{d}{dt} x(t) \right) + 2 x(t) = 11 - 4 t \quad (2.1.1.4)$$

The general solution of this equation is easily found using the method of undetermined coefficients. First generate the solution of the homogeneous equation.

> `aux:=r^2+3*r+2=0;`

`ev:=solve(aux, r);`

$$\text{aux} := r^2 + 3 r + 2 = 0$$

$$\text{ev} := -1, -2$$

(2.1.1.5)

> `xgh:=add(c[k]*exp(ev[k]*t), k=1..2);`

$$\text{xgh} := c_1 e^{-t} + c_2 e^{-2t}$$

(2.1.1.6)

Find a particular solution of the form  $x_p(t) = a_1 + a_2 t$ .

> `xtry:=a[1]+a[2]*t;`

`eqa:=eval(deq5, x(t)=xtry);`

`vala:=solve(identity(eqa, t), {a[1], a[2]});`

`xp:=eval(xtry, vala);`

$$\text{xtry} := a_1 + a_2 t$$

$$\text{eqa} := 3 a_2 + 2 a_1 + 2 a_2 t = 11 - 4 t$$

$$\text{vala} := \left\{ a_1 = \frac{17}{2}, a_2 = -2 \right\}$$

$$\text{xp} := \frac{17}{2} - 2 t$$

(2.1.1.7)

We conclude that the general solution of the differential equation

$$\frac{d^2}{dt^2} x(t) + 3 \left( \frac{d}{dt} x(t) \right) + 2 x(t) = 11 - 4 t$$

is given by

$$x_g(t) = c_1 e^{-t} + c_2 e^{-2t} + \frac{17}{2} - 2 t$$

> `xg:=xgh+xp;`

$$\text{xg} := c_1 e^{-t} + c_2 e^{-2t} + \frac{17}{2} - 2 t$$

(2.1.1.8)

The **corresponding**  $y_g(t)$  is obtained by substitution of  $x(t) = x_g(t)$  in the formula

$$y(t) = \frac{1}{10} \frac{d}{dt} x(t) + \frac{7}{10} x(t) - \frac{1}{10} t$$

> `yg:=eval(rhs(y_x), x(t)=xg);`

$$\text{yg} := \frac{3}{5} c_1 e^{-t} + \frac{1}{2} c_2 e^{-2t} + \frac{23}{4} - \frac{3}{2} t$$

(2.1.1.9)

Finally, we implement the initial conditions  $x(0) = 5$ ,  $y(0) = -4$  and solve for the constants  $c_1$  and  $c_2$ .

```
> eq1:=eval(xg, t=0)=5;
    eq2:=eval(yg, t=0)=-4;
    valc:=solve({eq1, eq2}, {c[1], c[2]});
```

$$eq1 := c_1 + c_2 + \frac{17}{2} = 5$$

$$eq2 := \frac{3}{5} c_1 + \frac{1}{2} c_2 + \frac{23}{4} = -4$$

$$valc := \left\{ c_1 = -80, c_2 = \frac{153}{2} \right\} \quad (2.1.1.10)$$

We conclude that the solution of the given initial value problem is given by

```
> x(t)=eval(xg, valc);
    y(t)=eval(yg, valc);
```

$$x(t) = -80 e^{-t} + \frac{153}{2} e^{-2t} + \frac{17}{2} - 2t$$

$$y(t) = -48 e^{-t} + \frac{153}{4} e^{-2t} + \frac{23}{4} - \frac{3}{2}t \quad (2.1.1.11)$$

### Solution 2

We can write the system

$$\frac{dx}{dt} = -7x + 10y + t$$

$$\frac{dy}{dt} = -3x + 4y + 1$$

in operator notation

$$(D + 7)[x] - 10[y] = t$$

$$3[x] + (D - 4)[y] = 1$$

and then solve this system by elimination much like we would solve an ordinary linear system in two unknowns.

```
> deq1:=diff(x(t), t)+7*x(t)-10*y(t)=t;
    deq2:=3*x(t)+diff(y(t), t)-4*y(t)=1;
```

$$deq1 := \frac{d}{dt} x(t) + 7x(t) - 10y(t) = t$$

$$deq2 := 3x(t) + \frac{d}{dt} y(t) - 4y(t) = 1 \quad (2.1.1.12)$$

First eliminate the variable  $x$ .

```
> deq3:=3*deq1;
    deq4:=diff(deq2, t)+7*deq2;
```

$$deq3 := 3 \left( \frac{d}{dt} x(t) \right) + 21x(t) - 30y(t) = 3t$$

$$deq4 := 3 \left( \frac{d}{dt} x(t) \right) + \frac{d^2}{dt^2} y(t) + 3 \left( \frac{d}{dt} y(t) \right) + 21x(t) - 28y(t) = 7 \quad (2.1.1.13)$$

```
> deq5:=deq3-deq4;
```

$$deq5 := -2y(t) - \left( \frac{d^2}{dt^2} y(t) \right) - 3 \left( \frac{d}{dt} y(t) \right) = 3t - 7 \quad (2.1.1.14)$$

Solve this differential equation using the method of undetermined coefficients. You know how to do that, right! For convenience we will just use the **dsolve** command.

```
> soly:=dsolve(deq5, y(t));
```

$$soly := y(t) = \frac{23}{4} - \frac{3}{2}t - e^{-2t} \_C1 + e^{-t} \_C2 \quad (2.1.1.15)$$

Let us replace the system generated variables  $\_C1$  and  $\_C2$  by  $b_1$  and  $b_2$ . (This has more than just an esthetic value)

```
> soly:=eval(soly, {seq(_C|k=b[k], k=1..2)});
```

$$soly := y(t) = \frac{23}{4} - \frac{3}{2}t - e^{-2t} b_1 + e^{-t} b_2 \quad (2.1.1.16)$$

Analogous to what we did in our first solution, we could substitute this into the second differential equation

$$3x(t) + \frac{d}{dt} y(t) - 4y(t) = 1$$

and solve directly for  $x(t)$ . Alternatively however, we can eliminate the variable  $y(t)$  and find  $x(t)$  that way.

```
> deq1;
```

```
deq2;
```

$$\frac{d}{dt} x(t) + 7x(t) - 10y(t) = t$$

$$3x(t) + \frac{d}{dt} y(t) - 4y(t) = 1 \quad (2.1.1.17)$$

```
> deq6:=diff(deq1, t)-4*deq1;
```

```
deq7:=-10*deq2;
```

$$deq6 := \frac{d^2}{dt^2} x(t) + 3 \left( \frac{d}{dt} x(t) \right) - 10 \left( \frac{d}{dt} y(t) \right) - 28x(t) + 40y(t) = 1 - 4t$$

$$deq7 := -30x(t) - 10 \left( \frac{d}{dt} y(t) \right) + 40y(t) = -10 \quad (2.1.1.18)$$

```
> deq8:=deq6-deq7;
```

$$deq8 := \frac{d^2}{dt^2} x(t) + 3 \left( \frac{d}{dt} x(t) \right) + 2x(t) = 11 - 4t \quad (2.1.1.19)$$

This differential equation can be solved using the method of undetermined coefficients. For expedience we once again use the **dsolve** routine.

```
> solx:=dsolve(deq8, x(t));
```

```
solx:=eval(solx, {seq(_C|k=a[k], k=1..2)});
```

$$solx := x(t) = \frac{17}{2} - 2t - e^{-2t} \_C1 + e^{-t} \_C2$$

$$\text{solx} := x(t) = \frac{17}{2} - 2t - e^{-2t} a_1 + e^{-t} a_2 \quad (2.1.1.20)$$

Now it is important to realize that the parameters  $a_1$ ,  $a_2$ ,  $b_1$ , and  $b_2$  are not independent.

Substitution of

$$x(t) = \frac{17}{2} - 2t - e^{-2t} a_1 + e^{-t} a_2$$

and

$$y(t) = \frac{23}{4} - \frac{3}{2}t - e^{-2t} b_1 + e^{-t} b_2$$

into the first differential equation

$$\frac{d}{dt} x(t) + 7x(t) - 10y(t) = t$$

yields

$$\begin{aligned} > \text{eq} := \text{eval}(\text{deq1}, \{\text{solx}, \text{soly}\}); \\ \text{eq} := -5e^{-2t} a_1 + 6e^{-t} a_2 + t + 10e^{-2t} b_1 - 10e^{-t} b_2 = t \end{aligned} \quad (2.1.1.21)$$

and because the functions  $e^{-2t}$  and  $e^{-t}$  are linearly independent, this yields

$$\begin{aligned} > \text{parsb} := \text{solve}(\text{identity}(\text{eq}, t), \{\text{b}[1], \text{b}[2]\}); \\ \text{parsb} := \left\{ b_1 = \frac{1}{2} a_1, b_2 = \frac{3}{5} a_2 \right\} \end{aligned} \quad (2.1.1.22)$$

Therefore, the general solution of the system is given by

$$\begin{aligned} x(t) &= \frac{17}{2} - 2t - e^{-2t} a_1 + e^{-t} a_2 \\ y(t) &= \frac{23}{4} - \frac{3}{2}t - \frac{1}{2} e^{-2t} a_1 + \frac{3}{5} e^{-t} a_2 \end{aligned}$$

$$\begin{aligned} > \text{xg} := \text{rhs}(\text{solx}); \\ \text{yg} := \text{eval}(\text{rhs}(\text{soly}), \text{parsb}); \\ \text{xg} &:= \frac{17}{2} - 2t - e^{-2t} a_1 + e^{-t} a_2 \\ \text{yg} &:= \frac{23}{4} - \frac{3}{2}t - \frac{1}{2} e^{-2t} a_1 + \frac{3}{5} e^{-t} a_2 \end{aligned} \quad (2.1.1.23)$$

Finally we again implement the initial conditions and arrive at the desired solution of the initial value problem.

$$\begin{aligned} > \text{eq1} := \text{eval}(\text{xg}, t=0)=5; \\ \text{eq2} := \text{eval}(\text{yg}, t=0)=-4; \\ \text{vala} := \text{solve}(\{\text{eq1}, \text{eq2}\}, \{\text{a}[1], \text{a}[2]\}); \\ \text{eq1} &:= \frac{17}{2} - a_1 + a_2 = 5 \\ \text{eq2} &:= \frac{23}{4} - \frac{1}{2} a_1 + \frac{3}{5} a_2 = -4 \\ \text{vala} &:= \left\{ a_1 = -\frac{153}{2}, a_2 = -80 \right\} \end{aligned} \quad (2.1.1.24)$$

We conclude that the solution of the given initial value problem is given by

**> x(t)=eval(xg, vala);**

**y(t)=eval(yg, vala);**

$$x(t) = -80 e^{-t} + \frac{153}{2} e^{-2t} + \frac{17}{2} - 2t$$

$$y(t) = -48 e^{-t} + \frac{153}{4} e^{-2t} + \frac{23}{4} - \frac{3}{2}t$$

**(2.1.1.25)**