

**Q12.7** No; Kinetic, Yes; Potential, No. For constant amplitude, the total energy  $\frac{1}{2}kA^2$  stays constant. The kinetic energy  $\frac{1}{2}mv^2$  would increase for larger mass if the speed were constant, but here the greater mass causes a decrease in frequency and in the average and maximum speed, so that the kinetic and potential energies at every point are unchanged.

**P12.2** (a)  $x = (5.00 \text{ cm})\cos\left(2t + \frac{\pi}{6}\right)$  At  $t = 0$ ,  $x = (5.00 \text{ cm})\cos\left(\frac{\pi}{6}\right) = \boxed{4.33 \text{ cm}}$

(b)  $v = \frac{dx}{dt} = -(10.0 \text{ cm/s})\sin\left(2t + \frac{\pi}{6}\right)$  At  $t = 0$ ,  $v = \boxed{-5.00 \text{ cm/s}}$

(c)  $a = \frac{dv}{dt} = -(20.0 \text{ cm/s}^2)\cos\left(2t + \frac{\pi}{6}\right)$  At  $t = 0$ ,  $a = \boxed{-17.3 \text{ cm/s}^2}$

(d)  $A = \boxed{5.00 \text{ cm}}$  and  $T = \frac{2\pi}{\omega} = \frac{2\pi}{2} = \boxed{3.14 \text{ s}}$

**P12.5** (a) At  $t = 0$ ,  $x = 0$  and  $v$  is positive (to the right). Therefore, this situation corresponds to  $x = A \sin \omega t$

and

$$v = v_i \cos \omega t$$

Since  $f = 1.50 \text{ Hz}$ ,

$$\omega = 2\pi f = 3.00\pi$$

Also,  $A = 2.00 \text{ cm}$ , so that

$$x = (2.00 \text{ cm})\sin 3.00\pi t$$

(b)  $v_{\max} = v_i = A\omega = 2.00(3.00\pi) = 6.00\pi \text{ cm/s} = \boxed{18.8 \text{ cm/s}}$

The particle has this speed at  $t = 0$  and next at  $t = \frac{T}{2} = \boxed{\frac{1}{3} \text{ s}}$

(c)  $a_{\max} = A\omega^2 = 2.00(3.00\pi)^2 = 18.0\pi^2 \text{ cm/s}^2 = \boxed{178 \text{ cm/s}^2}$

This positive value of acceleration first occurs at  $t = \frac{3}{4}T = \boxed{0.500 \text{ s}}$

(d) Since  $T = \frac{2}{3} \text{ s}$  and  $A = 2.00 \text{ cm}$ , the particle will travel 8.00 cm in this time.

Hence, in  $1.00 \text{ s} \left( = \frac{3}{2}T \right)$ , the particle will travel  $8.00 \text{ cm} + 4.00 \text{ cm} = \boxed{12.0 \text{ cm}}$ .

**P12.9**  $f = \frac{\omega}{2\pi} = \frac{1}{2\pi} \sqrt{\frac{k}{m}}$  or  $T = \frac{1}{f} = 2\pi \sqrt{\frac{m}{k}}$

Solving for  $k$ ,  $k = \frac{4\pi^2 m}{T^2} = \frac{4\pi^2(7.00 \text{ kg})}{(2.60 \text{ s})^2} = \boxed{40.9 \text{ N/m}}$ .

**P12.13** Choose the car with its shock-absorbing bumper as the system; by conservation of energy,

$$\frac{1}{2}mv^2 = \frac{1}{2}kx^2: \quad v = x\sqrt{\frac{k}{m}} = (3.16 \times 10^{-2} \text{ m})\sqrt{\frac{5.00 \times 10^6}{10^3}} = \boxed{2.23 \text{ m/s}}$$

- P12.15 (a) Energy is conserved for the block-spring system between the maximum-displacement and the half-maximum points:

$$(K+U)_i = (K+U)_f \quad 0 + \frac{1}{2}kA^2 = \frac{1}{2}mv^2 + \frac{1}{2}kx^2$$

$$\frac{1}{2}(6.50 \text{ N/m})(0.100 \text{ m})^2 = \frac{1}{2}m(0.300 \text{ m/s})^2 + \frac{1}{2}(6.50 \text{ N/m})(5.00 \times 10^{-2} \text{ m})^2$$

$$32.5 \text{ mJ} = \frac{1}{2}m(0.300 \text{ m/s})^2 + 8.12 \text{ mJ} \quad m = \frac{2(24.4 \text{ mJ})}{9.0 \times 10^{-2} \text{ m}^2/\text{s}^2} = \boxed{0.542 \text{ kg}}$$

(b)  $\omega = \sqrt{\frac{k}{m}} = \sqrt{\frac{6.50 \text{ N/m}}{0.542 \text{ kg}}} = 3.46 \text{ rad/s} \quad \therefore T = \frac{2\pi}{\omega} = \frac{2\pi \text{ rad}}{3.46 \text{ rad/s}} = \boxed{1.81 \text{ s}}$

(c)  $a_{\max} = A\omega^2 = 0.100 \text{ m}(3.46 \text{ rad/s})^2 = \boxed{1.20 \text{ m/s}^2}$

P12.17 (a)  $E = \frac{1}{2}kA^2 = \frac{1}{2}(35.0 \text{ N/m})(4.00 \times 10^{-2} \text{ m})^2 = \boxed{28.0 \text{ mJ}}$

(b)  $|v| = \omega\sqrt{A^2 - x^2} = \sqrt{\frac{k}{m}}\sqrt{A^2 - x^2}$

$$|v| = \sqrt{\frac{35.0}{50.0 \times 10^{-3}}} \sqrt{(4.00 \times 10^{-2})^2 - (1.00 \times 10^{-2})^2} = \boxed{1.02 \text{ m/s}}$$

(c)  $\frac{1}{2}mv^2 = \frac{1}{2}kA^2 - \frac{1}{2}kx^2 = \frac{1}{2}(35.0) \left[ (4.00 \times 10^{-2})^2 - (3.00 \times 10^{-2})^2 \right] = \boxed{12.2 \text{ mJ}}$

(d)  $\frac{1}{2}kx^2 = E - \frac{1}{2}mv^2 = \boxed{15.8 \text{ mJ}}$

P12.7 The proposed solution  $x(t) = x_i \cos \omega t + \left(\frac{v_i}{\omega}\right) \sin \omega t$

implies velocity  $v = \frac{dx}{dt} = -x_i \omega \sin \omega t + v_i \cos \omega t$

and acceleration  $a = \frac{dv}{dt} = -x_i \omega^2 \cos \omega t - v_i \omega \sin \omega t = -\omega^2 \left( x_i \cos \omega t + \left(\frac{v_i}{\omega}\right) \sin \omega t \right) = -\omega^2 x$

- (a) The acceleration being a negative constant times position means we do have SHM, and its angular frequency is  $\omega$ . At  $t=0$  the equations reduce to  $x = x_i$  and  $v = v_i$ , so they satisfy all the requirements.

(b)  $v^2 - ax = (-x_i \omega \sin \omega t + v_i \cos \omega t)^2 - (-x_i \omega^2 \cos \omega t - v_i \omega \sin \omega t) \left( x_i \cos \omega t + \left(\frac{v_i}{\omega}\right) \sin \omega t \right)$

$$v^2 - ax = x_i^2 \omega^2 \sin^2 \omega t - 2x_i v_i \omega \sin \omega t \cos \omega t + v_i^2 \cos^2 \omega t$$

$$+ x_i^2 \omega^2 \cos^2 \omega t + x_i v_i \omega \cos \omega t \sin \omega t + x_i v_i \omega \sin \omega t \cos \omega t + v_i^2 \sin^2 \omega t = x_i^2 \omega^2 + v_i^2$$

So this expression is constant in time. On one hand, it must keep its original value  $v_i^2 - a_i x_i$ . On the other hand, if we evaluate it at a turning point where  $v=0$  and  $x=A$ , it is  $A^2 \omega^2 + 0^2 = A^2 \omega^2$ . Thus it is proved.

\*P12.20 (a)  $y_f = y_i + v_{y_i}t + \frac{1}{2}a_y t^2$   
 $-11 \text{ m} = 0 + 0 + \frac{1}{2}(-9.8 \text{ m/s}^2)t^2$   
 $t = \sqrt{\frac{22 \text{ m} \cdot \text{s}^2}{9.8 \text{ m}}} = \boxed{1.50 \text{ s}}$

- (b) Take the initial point where she steps off the bridge and the final point at the bottom of her motion.

$$(K + U_g + U_s)_i = (K + U_g + U_s)_f$$

$$0 + mgy + 0 = 0 + 0 + \frac{1}{2}kx^2$$

$$65 \text{ kg} \cdot 9.8 \text{ m/s}^2 \cdot 36 \text{ m} = \frac{1}{2}k(25 \text{ m})^2$$

$$k = \boxed{73.4 \text{ N/m}}$$

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- (c) The spring extension at equilibrium is  $x = \frac{F}{k} = \frac{65 \text{ kg} \cdot 9.8 \text{ m/s}^2}{73.4 \text{ N/m}} = 8.68 \text{ m}$ , so this point is  $11 + 8.68 \text{ m} = \boxed{19.7 \text{ m below the bridge}}$  and the amplitude of her oscillation is  $36 - 19.7 = 16.3 \text{ m}$ .

(d)  $\omega = \sqrt{\frac{k}{m}} = \sqrt{\frac{73.4 \text{ N/m}}{65 \text{ kg}}} = \boxed{1.06 \text{ rad/s}}$

- (e) Take the phase as zero at maximum downward extension. We find what the phase was 25 m higher, where  $x = -8.68 \text{ m}$ :

$$\text{In } x = A \cos \omega t, \quad 16.3 \text{ m} = 16.3 \text{ m} \cos 0$$

$$-8.68 \text{ m} = 16.3 \text{ m} \cos\left(1.06 \frac{t}{\text{s}}\right) \quad 1.06 \frac{t}{\text{s}} = -122^\circ = -2.13 \text{ rad}$$

$$t = -2.01 \text{ s}$$

Then  $\boxed{+2.01 \text{ s}}$  is the time over which the spring stretches.

- (f) total time =  $1.50 \text{ s} + 2.01 \text{ s} = \boxed{3.50 \text{ s}}$